

# Diverse Worlds of Belief Propagation

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#### Outline

- Three Problems
  - Error Correction
  - Particle Tracking
  - Power Grid
- 2 One Method
  - Common Language (Graphical Models) & Common Questions
  - Message Passing/ Belief Propagation
  - ... and beyond ... (theory)
- Results
  - Error Correction
  - Particle Tracking
  - Power Grid



#### **Error Correction**

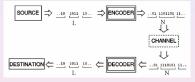








#### Scheme:



#### Example of Additive White Gaussian Channel:

$$P(\mathbf{x}_{out}|\mathbf{x}_{in}) = \prod_{i=bits} p(x_{out;i}|x_{in;i})$$
$$p(x|y) \sim \exp(-s^2(x-y)^2/2)$$

- Channel is noisy "black box" with only statistical information available
- Encoding: use redundancy to redistribute damaging effect of the noise
- Decoding [Algorithm]: reconstruct most probable codeword by noisy (polluted) channel



## Low Density Parity Check Codes

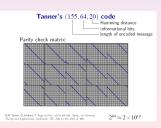


- N bits, M checks, L = N M information bits example: N = 10, M = 5, L = 5
- 2<sup>L</sup> codewords of 2<sup>N</sup> possible patterns
- Parity check: Âv = c = 0 example:

LDPC = graph (parity check matrix) is sparse



Almost a tree! [Sparse Graph/Code]



◆ロ → ◆昼 → ◆ き → き 目 = か へ ○

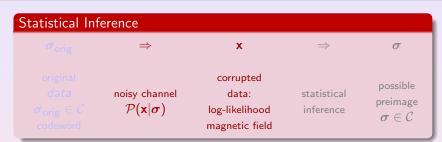


#### Maximum Likelihood

#### Marginal Probability

$$rg \max_{m{\sigma}} \mathcal{P}(m{\sigma}|\mathbf{x}) \qquad \qquad rg \max_{m{\sigma}_i} \sum_{m{\sigma} \setminus m{\sigma}_i} \mathcal{P}(\mathbf{x}|m{\sigma})$$



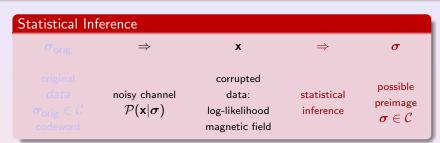


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#### 

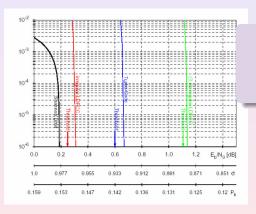
$$\sigma = (\sigma_1, \dots, \sigma_N), \quad N \text{ finite}, \quad \sigma_i = \pm 1 \text{ (example)}$$

#### Maximum Likelihood

#### Marginal Probability

$$rg \max_{m{\sigma}} \mathcal{P}(m{\sigma} | \mathbf{x}) \qquad \qquad rg \max_{\sigma_i} \sum_{m{\sigma} \setminus \sigma_i} \mathcal{P}(\mathbf{x} | m{\sigma})$$

#### Shannon Transition

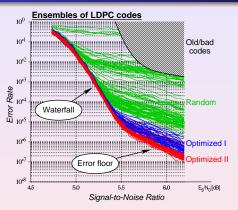


# Existence of an efficient MESSAGE PASSING [belief propagation] decoding

makes LDPC codes special!

- Phase Transition
- Ensemble of Codes [analysis & design]
- Thermodynamic limit but ...

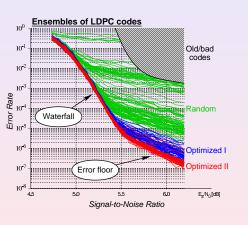
#### Error-Floor



- T. Richardson '03 (EF)
- Density evolution does not apply (to EF)

- BER vs SNR = measure of performance
- Finite size effects
- Waterfall → Error-floor
- Error-floor typically emerges due to sub-optimality of decoding,
   i.e. due to unaccounted loops
- Monte-Carlo is useless at FER  $\lesssim 10^{-8}$

# Error-floor Challenges

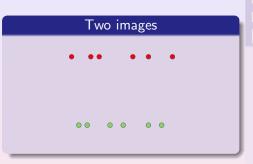


- Understanding the Error Floor (Inflection point, Asymptotics), Need an efficient method to analyze error-floor
- Improving Decoding
- Constructing New Codes

Dance in Turbulence [movie]

Learn the flow from tracking particles

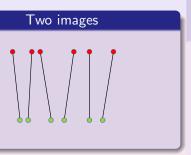




## Particle Image Velocimetry & Lagrangian Particle Tracking [standard solution]

- Take snapshots often = Avoid trajectory overlap
- Consequence = A lot of data
- Gigabit/s to monitor a two-dimensional slice of a 10cm<sup>3</sup> experimental cell with a pixel size of 0.1mm and exposition time of 1ms
- Still need to "learn" velocity (diffusion) from matching

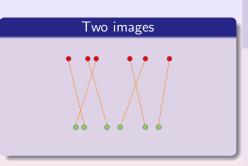
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- Use our (turbulence community) knowledge of Lagrangian evolution
- Focus on learning (rather than ma



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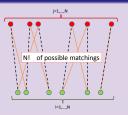


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#### Two images



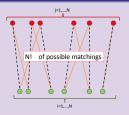
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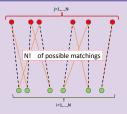
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# Lagrangian Dynamics under the Viscous Scale

#### Plausible (for PIV) Modeling Assumptions

- Particles are normally seed with mean separation few times smaller than the viscous scale.
- The Lagrangian velocity at these scales is spatially smooth.
- Moreover the velocity gradient,  $\hat{s}$ , at these scales and times is frozen (time independent).

#### Batchelor (diffusion + smooth advection) Model

- Trajectory of i's particles obeys:  $d\mathbf{r}_i(t)/dt = \hat{s}\mathbf{r}_i(t) + \boldsymbol{\xi}_i(t)$
- $tr(\hat{s}) = 0$  incompressible flow
- $\langle \xi_i^{\alpha}(t_1)\xi_i^{\beta}(t_2)\rangle = \kappa \delta_{ij}\delta^{\alpha\beta}\delta(t_1-t_2)$



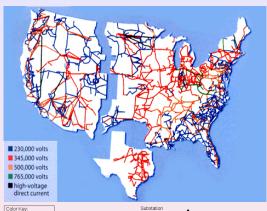
# Inference & Learning

#### Main Task: Learning parameters of the flow and of the medium

- Given positions of N identical particles at t=0 and t=1:  $\forall i,j=1,\cdots,N,\quad \mathbf{x}_i=\mathbf{r}_i(0)$  and  $\mathbf{y}^j=\mathbf{r}_i(1)$
- To output MOST PROBABLE values of the flow,  $\hat{s}$ , and the medium,  $\kappa$ , characterizing the inter-snapshot span:  $\theta = (\hat{s}; \kappa)$ . [Matchings are hidden variables.]

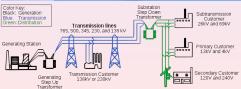
#### Sub-task: Inference [reconstruction] of Matchings

- ullet Given parameters of the medium and the flow,  $oldsymbol{ heta}$
- To reconstruct Most Probable matching between identical particles in the two snapshots ["ground state"]
- Even more generally Probabilistic Reconstruction: to assign probability to each matchings and evaluate marginal probabilities ["magnetizations"]



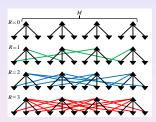
# US power grid

The greatest Engineering Achievement of the 20<sup>th</sup> century

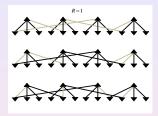


will require smart revolution in the 21<sup>st</sup> century

#### Optimization & Control of Power Grid [L. Zdeborova, A. Decelle, MC '09]



A: R = 0; 1; 2; 3. Graph samples. Ancillary connections to foreign generators/consumers are shown in color.



B: R=1. Three valid (SAT) configurations (shown in black, the rest is in gray) for a sample graph shown in Fig. A.

- Can the anchillary lines (redundancy) help?
- Design and efficient switching algorithm for finding SAT solution.

#### Outline

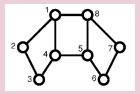
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### Boolean Graphical Models = The Language

#### Forney style - variables on the edges

$$\mathcal{P}(\vec{\sigma}) = Z^{-1} \prod_{a} f_{a}(\vec{\sigma}_{a})$$

$$Z = \sum_{\sigma} \prod_{a} f_{a}(\vec{\sigma}_{a})$$
partition function



$$f_a \ge 0$$
 $\sigma_{ab} = \sigma_{ba} = \pm 1$ 
 $\vec{\sigma}_1 = (\sigma_{12}, \sigma_{14}, \sigma_{18})$ 
 $\vec{\sigma}_2 = (\sigma_{12}, \sigma_{23})$ 

#### Objects of Interest

- Most Probable Configuration = Maximum Likelihood = Ground State:  $\arg \max \mathcal{P}(\vec{\sigma})$
- Marginal Probability: e.g.  $\mathcal{P}(\sigma_{ab}) \equiv \sum_{\vec{\sigma} \setminus \sigma_{ab}} \mathcal{P}(\vec{\sigma})$
- Partition Function: Z

# Complexity & Algorithms

- How many operations are required to evaluate a graphical model of size N?
- What is the exact algorithm with the least number of operations?
- If one is ready to trade optimality for efficiency, what is the best (or just good) approximate algorithm he/she can find for a given (small) number of operations?
- Given an approximate algorithm, how to decide if the algorithm is good or bad? What is the measure of success?
- How one can systematically improve an approximate algorithm?
- Linear (or Algebraic) in N is EASY, Exponential is DIFFICULT

# Easy & Difficult Boolean Problems

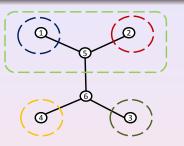
#### EASY

- Any graphical problems on a tree (Bethe-Peierls, Dynamical Programming, BP, TAP and other names)
- Ground State of a Rand. Field Ferrom. Ising model on any graph
- Partition function of a planar Ising model
- Finding if 2-SAT is satisfiable
- Decoding over Binary Erasure Channel = XOR-SAT
- Some network flow problems (max-flow, min-cut, shortest path, etc)
- Minimal Perfect Matching Problem
- Some special cases of Integer Programming (TUM)

Typical graphical problem, with loops and factor functions of a general position, is DIFFICULT

#### BP is Exact on a Tree

### Bethe '35, Peierls '36



$$Z_{51}(\sigma_{51}) = f_1(\sigma_{51}), \quad Z_{52}(\sigma_{52}) = f_2(\sigma_{52}),$$

$$Z_{63}(\sigma_{63}) = f_3(\sigma_{63}), \quad Z_{64}(\sigma_{64}) = f_4(\sigma_{64})$$

$$Z_{65}(\sigma_{56}) = \sum_{\vec{\sigma}_5 \setminus \sigma_{56}} f_5(\vec{\sigma}_5) Z_{51}(\sigma_{51}) Z_{52}(\sigma_{52})$$

$$Z = \sum_{\vec{\sigma}_6} f_6(\vec{\sigma}_6) Z_{63}(\sigma_{63}) Z_{64}(\sigma_{64}) Z_{65}(\sigma_{65})$$

$$Z_{ba}(\sigma_{ab}) = \sum_{\vec{\sigma}_a \setminus \sigma_{ab}} f_a(\vec{\sigma}_a) Z_{ac}(\sigma_{ac}) Z_{ad}(\sigma_{ad}) \ \Rightarrow \ Z_{ab}(\sigma_{ab}) = A_{ab} \exp(\eta_{ab} \sigma_{ab})$$

#### **Belief Propagation Equations**

$$\sum_{\vec{\sigma}} f_{a}(\vec{\sigma}_{a}) \exp(\sum_{c \in a} \eta_{ac} \sigma_{ac}) \left(\sigma_{ab} - \tanh\left(\eta_{ab} + \eta_{ba}\right)\right) = 0$$

e.g. Thouless-Anderson-Palmer (1977) Eqs.

# Belief Propagation (BP) and Message Passing

- Apply what is exact on a tree (the equation) to other problems on graphs with loops [heuristics ... but a good one]
- To solve the system of N equations is EASIER then to count (or to choose one of) 2<sup>N</sup> states.

#### Bethe Free Energy formulation of BP [Yedidia, Freeman, Weiss '01]

Minimize the Kubblack-Leibler functional

$$\mathcal{F}\{b(\{\sigma\})\} \equiv \sum_{\{\sigma\}} b(\{\sigma\}) \ln \frac{b(\{\sigma\})}{\mathcal{L}(\{\sigma\})}$$

Difficult/Exact

under the following "almost variational" substitution" for beliefs:

$$b(\{\sigma\}) pprox rac{\prod_i b_i(\sigma_i) \prod_j b^j(\sigma^j)}{\prod_{(i,i)} b^j_i(\sigma^j_i)}$$
 [tracking]

Easy/Approximate



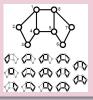
- Message Passing is a (graph) Distributed Implementation of BP
- Graphical Models = the language

# Beyond BP [MC, V. Chernyak '06-'09 + J. Johnson '09]

#### Only mentioning briefly today

#### Loop Calculus/Series:

$$Z = \sum_{\vec{\sigma}_{\sigma}} \prod_{a} f_{a}(\vec{\sigma}_{a}) = Z_{BP} \left( 1 + \sum_{C} r(C) \right),$$
 each  $r_{C}$  is expressed solely in terms of BP marginals



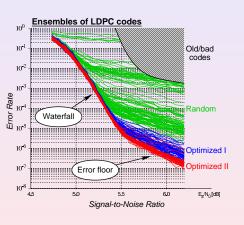
- BP is a Gauge. There are other interesting choices of the Gauges.
- Loop Series for Gaussian Integrals, Fermions, etc.
- Planar and Surface Graphical Models which are Easy [alas dimer].
   Holographic Computations. Matchgates. Quantum Theory of Computations.
- Orbit product for Gaussian GM [J. Johnson's SFI coll in three week]

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# Error-floor Challenges



- Understanding the Error Floor (Inflection point, Asymptotics), Need an efficient method to analyze error-floor
- ... i.e. an efficient method to analyze rare-events [BP failures] ⇒

# Optimal Fluctuation (Instanton) Approach for Extracting Rare but Dominant Events



Ed was unlucky enough to find the needle in the haystack!

# Optimal Fluctuation (Instanton) Approach for Extracting Rare but Dominant Events



Ed was unlucky enough to find the needle in the haystack!



You were right: There's a needle in this haystack...

#### Pseudo-codewords and Instantons

#### Error-floor is caused by Pseudo-codewords:

Wiberg '96; Forney et.al'99; Frey et.al '01; Richardson '03; Vontobel, Koetter '04-'06

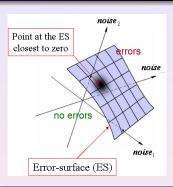
#### Instanton = optimal conf of the noise

$$BER = \int d(noise) WEIGHT(noise)$$

$$BER \sim WEIGHT \left( \begin{array}{c} optimal\ conf \\ of\ the\ noise \end{array} \right)$$

optimal conf of the noise = Point at the ES closest to "0"

Instantons are decoded to Pseudo-Codewords



#### Instanton-amoeba

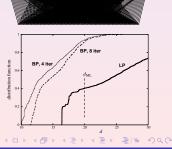
= optimization algorithm Stepanov, et.al '04,'05 Stepanov, Chertkov '06

# Efficeint Instanton Search Algorithm

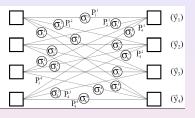
[MC, M. Stepanov '07; MC, MC, S. Chillapagari, B. Vasic '08-'09]

$$\mathsf{BER} \approx \mathsf{max}_{\mathsf{noise}} \underbrace{\mathsf{min}_{\mathsf{output}} \mathsf{Weight}(\mathsf{noise}; \mathsf{output})}_{\mathsf{decoding}} \\ \mathsf{Error} \; \mathsf{Surface}$$

- Developed Efficient Alg. for LP-Instanton Search. The output is the spectra of the dangerous pseudo-codewords
- Started to design Better Decoding = Improved LP/BP +
- Started to design new codes



# Tracking Particles as a Graphical Model



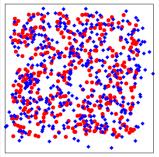
$$\mathcal{L}(\{\sigma\}|\boldsymbol{\theta}) = C(\{\sigma\}) \prod_{(i,j)} \left[ P_i^j \left( \mathbf{x}_i, \mathbf{y}^j | \boldsymbol{\theta} \right) \right]^{\sigma_i^j}$$

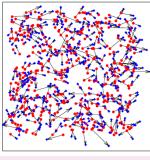
$$C\left(\left\{\sigma\right\}\right) \equiv \prod_{j} \delta\left(\sum_{i} \sigma_{i}^{j}, 1\right) \prod_{i} \delta\left(\sum_{j} \sigma_{i}^{j}, 1\right)$$

#### Surprising Exactness of BP for ML-assignement

- Exact Polynomial Algorithms (auction, Hungarian) are available for the problem
- Generally BP is exact only on a graph without loops [tree]
- In this [Perfect Matching on Bipartite Graph] case it is still exact in spite of many loops!! [Bayati, Shah, Sharma '08], also Linear Programming/TUM interpretation [MC '08]

## Can you guess who went where?





- N particles are placed uniformly at random in a d-dimensional box of size N<sup>1/d</sup>
- Choose  $\theta = (\kappa, \mathbf{s})$  in such a way that after rescaling,  $\hat{\mathbf{s}}^* = \hat{\mathbf{s}} N^{1/d}$ ,  $\kappa^* = \kappa$ , all the rescaled parameters are O(1).
- Produce a stochastic map for the N particles from the original image to respective positions in the consecutive image.

- N = 400 particles. 2D.
- Actual values:  $\kappa = 1.05$ ,  $a^* = 0.28$ ,  $b^* = 0.54$ ,  $c^* = 0.24$
- Output of OUR LEARNING algorithm: [accounts for multiple matchings !!]  $\kappa_{BP} = 1$ ,  $a_{BP} = 0.32$ ,  $b_{BP} = 0.55$ ,  $c_{BP} = 0.19$  [within the "finite size" error]

# Combined Message Passing with Parameters' Update

#### Fixed Point Equations for Messages

- $\bullet \ \ \mathsf{BP} \ \ \mathsf{equations:} \ \ \overline{h}^{i \to j} = -\tfrac{1}{\beta} \ln \textstyle \sum_{k \neq j} P_i^k e^{\beta \underline{h}^{k \to i}} \ ; \ \underline{h}^{j \to i} = -\tfrac{1}{\beta} \ln \textstyle \sum_{k \neq i} P_k^j e^{\beta \overline{h}^{k \to j}}$
- BP estimation for  $Z_{BP}(\theta) = Z(\theta|\mathbf{h} \text{ solves BP eqs. at } \beta = 1)$
- MPA estimation for  $Z_{MPA}(\theta) = Z(\theta|\mathbf{h} \text{ solves BP eqs. at } \beta = \infty)$

$$Z(\boldsymbol{\theta}|\mathbf{h};\boldsymbol{\beta}) = \textstyle\sum_{(jj)} \ln \left( 1 + P_{i}^{j} e^{\beta \overline{h}^{i \to j} + \beta \underline{h}^{j \to i}} \right) - \textstyle\sum_{i} \ln \left( \textstyle\sum_{j} P_{i}^{j} e^{\beta \underline{h}^{j \to i}} \right) - \textstyle\sum_{j} \ln \left( \textstyle\sum_{i} P_{i}^{j} e^{\beta \overline{h}^{i \to j}} \right)$$

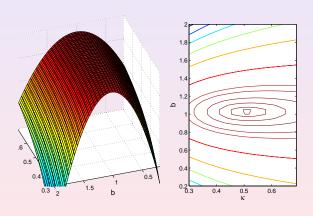
#### Learning: $\operatorname{argmin}_{\theta} Z(\theta)$

- Solved using Newton's method in combination with message-passing: after each Newton step, we update the messages
- Even though (theoretically) the convergence is not guaranteed, the scheme always converges
- Complexity [in our implementation] is  $O(N^2)$ , even though reduction to O(N) is straightforward



# Quality of the Predicition [is good]

2D. 
$$a^* = b^* = c^* = 1$$
,  $\kappa^* = 0.5$ .  $N = 200$ .



- The BP Bethe free energy vs κ and b. Every point is obtained by minimizing wrt a, c
- Perfect maximum at b=1 and  $\kappa=0.5$  achieved at  $a_{BP}=1.148(1)$ ,  $b_{BP}=1.026(1)$ ,  $c_{BP}=0.945(1)$ ,  $\kappa_{BP}=0.509(1)$ .

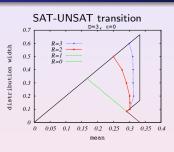
We also have a "random distance" model [ala random matching of Mezard, Parisi '86-'01] providing a theory support for using BP in the reconstruction/learning algorithms.

#### We are working on

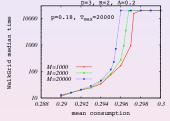
- Applying the algorithm to real particle tracking in turbulence experiments
- Extending the approach to learning multi-scale velocity field and possibly from multiple consequential images
- Going beyond BP [improving the quality of tracking]

# Message-Passing Switching Algorithm for the grid model with ancillary lines









- To analyze the SAT-UNSAT transition We solved Cavity Equations (averaged BP) with Population Dynamics Algorithm
- We developed WalkGrid (greedy search) algorithm which finds SAT-switching efficiently

#### We are working on

- Application of the approach to more realistic grids
- Extending the story beyond "the commodity flow" approach towards accounting for AC/DC specifics of the power flows
- Switching vs Contingency. Off-line games. Control Algorithms.
- ... this research is a part of a new DR project at LANL on "Optimization and Control Theory for Smart Grids"

#### **Bottom Line**

- Applications of Belief Propagation (and its distributed iterative realization, Message Passing) are diverse and abundant
- BP/MP is also advantageous, thanks to existence of very reach and powerful tree-like, sparse analysis techniques [physics, CS, statistics]
- BP/MP has great theory and application potential for improvements [account for loops]
- BP/MP can be combined with other techniques (e.g. Markov Chain, planar inference, etc) and in this regards it represents the tip of the iceberg called "Science of Algorithms"

#### References

http://cnls.lanl.gov/~chertkov/pub.htm

http://cnls.lnl.gov/~chertkov/Talks/IT/ColBP.pdf

